

Motivation

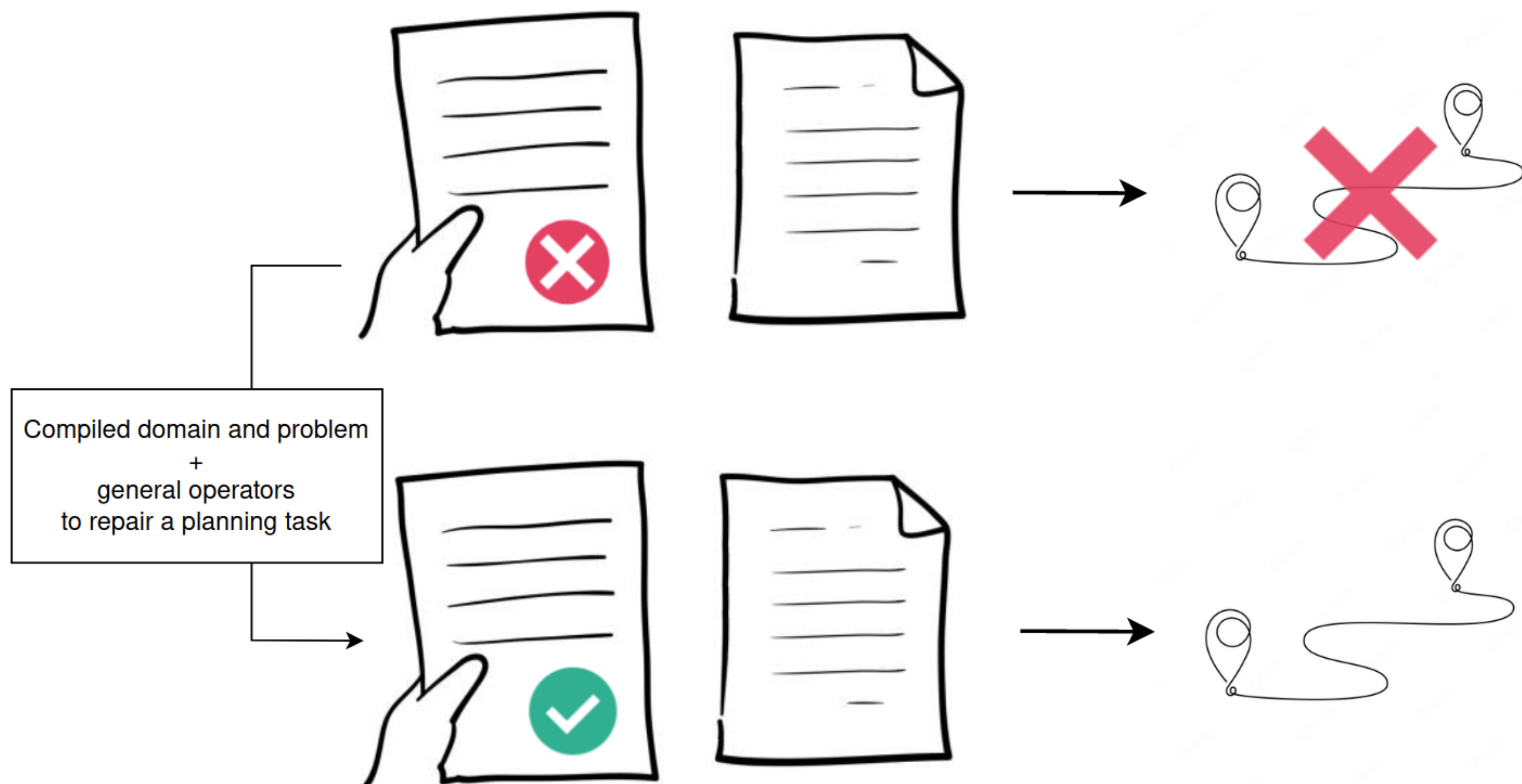
- Automated planning typically assumes an accurate task specification, defined by a domain and a problem description, specified in PDDL
- Modeling a planning task is complex and error-prone, requiring broad knowledge of the domain, the current task, and the formal language
- An incomplete model may render the planning task unsolvable

Explaining the absence of a solution in such cases is essential to support humans in the development of automated planning tasks.

Approach to repair flawed domains

The unsolvable task is compiled into a new planning task where:

- Actions can be repaired to **insert possible missing effects**
- The solution is a plan that achieves the goals of the original problem while at the same time repairs the original actions



Input Example

A Blocksworld planning domain with the following missing effects:

- holding** effect from the *pick-up* action
- on** effect from the *stack* action
- holding** effect from the *unstack* action

```
(:action pick-up
  :parameters (?x - block)
  :precondition (and (clear ?x) (ontable ?x) (handempty))
  :effect (and (not (ontable ?x))(not (clear ?x))(not (handempty))))
```

Classical Planning Compilation

- New predicates to represent the planning task elements
- Control predicates to manage the repair process
- New actions to modify the original actions: fix, add-fix, del-fix, close
- Internal process to repair an action: open → link new effects → close
- Bias to guide the reparation using action costs

```
(:action fix___adding_different
  :parameters (?p - predicate ?a - action)
  :precondition (and (current-action ?a)
    (functor ?p)
    (not (checked ?a))
    (not (patched ?a))
    (not (add_eff ?p ?a))
    (not (del_eff ?p ?a))
    (open))
  :effect (and (fix ?a ?p)
    (patched ?a)
    (increase (total-cost) X)))

(:action add-fix___1par
  :parameters (?p - predicate ?a - action
    ?o - objectdomain ?v - typedomain)
  :precondition (and (current-action ?a)
    (fix ?a ?p) (pred_1var ?p ?v)
    (type ?v ?o) (used ?o)
    (not (used ?p))
    (not (del_added ?p ?a))
    (not (goal_1var ?p ?o))
    (not (in_statel ?p ?o)))
  :effect (and (already-fixed)
    (in_statel ?p ?o)
    (used ?p)))
```

Output Example

The result of the compiled planning task is a plan that includes the reparations made in the domain to achieve the goals.

```
(unstack b4 b3)
(fix___adding_different holding unstack)
(add-fix___1par holding unstack b4 t_block)
(completed_fixed unstack)
(put-down b4)
(completed_nofixed put-down)
(unstack b3 b2)
(add-fix___1par holding unstack b3 t_block)
(completed_fixed unstack)
(stack b3 b4)
(fix___adding_different on stack)
(add-fix___2par_goal on stack b3 b4 t_block t_block)
(completed_fixed stack)
(pick-up b1)
(fix___adding_different holding pick-up)
(add-fix___1par holding pick-up b1 t_block)
(completed_fixed pick-up)
(stack b1 b3)
(add-fix___2par_goal on stack b1 b3 t_block t_block)
(completed_fixed stack)
```

The plan is parsed and shown in the interface as repair suggestions to the original domain...

PDDL Domain Repair

A Planning Approach to Repair Domains with Incomplete Action Effects

Alba Gragera, Raquel Fuentetaja, Ángel García-Olaya, Fernando Fernández

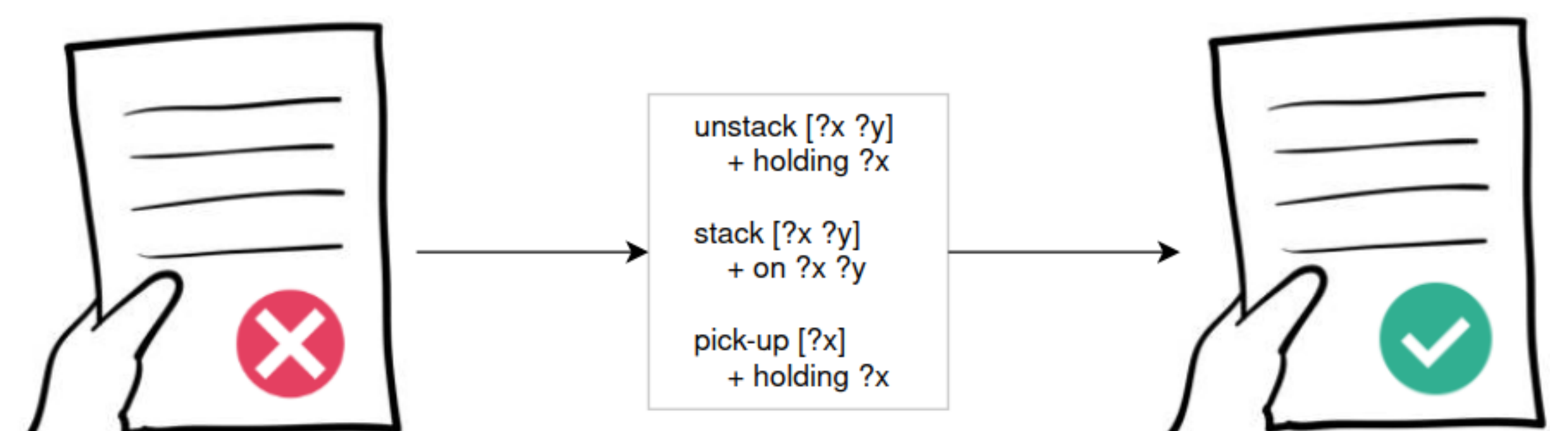
ICAPS 2023



Try these suggestions:

1. Repair the **unstack** action with a **(holding ?x)** positive effect
2. Repair the **stack** action with a **(on ?x ?y)** positive effect
3. Repair the **pick-up** action with a **(holding ?x)** positive effect

... ensuring that they make the task solvable.



Conclusions

- A fairly accurate reparation without requiring additional information from the user, only a domain and a single problem
- The lack of information about the number and location of flaws, as well as the user's mental model, can lead to estimated repairs